

Review Packet 1

1. For each of the following, write the vector or matrix that is specified:

a. $\mathbf{e}_3 \in \mathbb{R}^4$

b. $\mathbf{D} = \text{diag}\{2, \sqrt{3}, -1\}$

c. $\mathbf{e} \in \mathbb{R}^3$

d. \mathbf{I}_2

a) $\begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$

b) $\begin{pmatrix} 2 & 0 & 0 \\ 0 & \sqrt{3} & 0 \\ 0 & 0 & -1 \end{pmatrix}$

c) $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

d) $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

2. For each of the following matrices and vectors, give their dimension. Label each as a matrix or vector. For each matrix, indicate whether the matrix is square or rectangular.

a.

$\mathbf{A} = \begin{pmatrix} 2 & 3 & -1 \\ 1 & -1 & 1 \\ 2 & 2 & 1 \end{pmatrix}$ 3×3 square matrix

b.

$\mathbf{h} = \begin{pmatrix} -1 \\ -4 \\ 1 \\ 2 \end{pmatrix}$ 4×1 vector

c.

$\mathbf{B} = \begin{pmatrix} B_{11} & B_{12} & B_{13} \\ B_{21} & B_{22} & B_{23} \\ B_{31} & B_{32} & B_{33} \\ B_{41} & B_{42} & B_{43} \end{pmatrix}$ 4×3 rectangular matrix

d.

$\mathbf{A} = [A_{ij}]$ where $i = 1, 2, 3$ and $j = 1, 2$ 3×2 rectangular matrix

3. Specify whether the following augmented matrices are in row-echelon form (REF), reduced row-echelon form (RREF), or neither:

a. $\left(\begin{array}{ccc|c} 3 & 2 & 1 & 2 \\ 0 & 2 & 0 & 1 \\ 0 & 0 & 1 & 5 \end{array} \right)$ REF (could eliminate (1,2)-element and (1,3)-element)

b. $\left(\begin{array}{ccc|c} 3 & 2 & 1 & 2 \\ 0 & 2 & 0 & 1 \\ 0 & 4 & 0 & 0 \end{array} \right)$ neither

c. $\left(\begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right)$ RREF

d. $\left(\begin{array}{ccc|c} 1 & 2 & 0 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right)$ REF

4. (True/False) The normal equations are used to find the ordinary least-squares solution to an inconsistent system of equations.

TRUE.

5. If the matrix equation $\mathbf{M}\mathbf{v} = \mathbf{b}$ is inconsistent, what alternative equation should I solve to find a solution $\hat{\mathbf{v}}$ such that $\mathbf{M}\hat{\mathbf{v}} = \hat{\mathbf{b}}$ is as close to \mathbf{b} as possible in the sense that it minimizes the sum of squared error:

$$SSE = \sum_{i=1}^n (\hat{\mathbf{b}}_i - \mathbf{b}_i)^2$$

$$\mathbf{M}^T \mathbf{M} \hat{\mathbf{v}} = \mathbf{M}^T \mathbf{b} \quad (\text{the normal eqns})$$

6. Answer the following questions about each matrix

$$\mathbf{A} = \begin{pmatrix} 4 & 5 & 2 \\ 5 & 3 & 1 \\ 2 & 1 & -2 \end{pmatrix} \quad \mathbf{B} = \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 2 & 1 & 0 \\ 0 & 1 & -1 & 1 \end{pmatrix}$$

- a. Is the matrix square?

A Yes B No

- b. What is the transpose of the matrix?

$$\mathbf{A}^T = \mathbf{A}$$

$$\mathbf{B}^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 1 & 1 & -1 \\ -1 & 0 & 1 \end{pmatrix}$$

- c. Is the matrix symmetric?

A yes B no

- d. If possible, name the diagonal elements of the matrix.

A 4, 3, -2 B n.p.

- e. If possible, compute the Trace of the matrix.

$4 + 3 - 2$
A = 5 B n.p.

- f. Can the product \mathbf{AB} be computed? If so, what is the size of the result?

yes 3x4

- g. Can the product \mathbf{BA} be computed? If so, what is the size of the result?

No

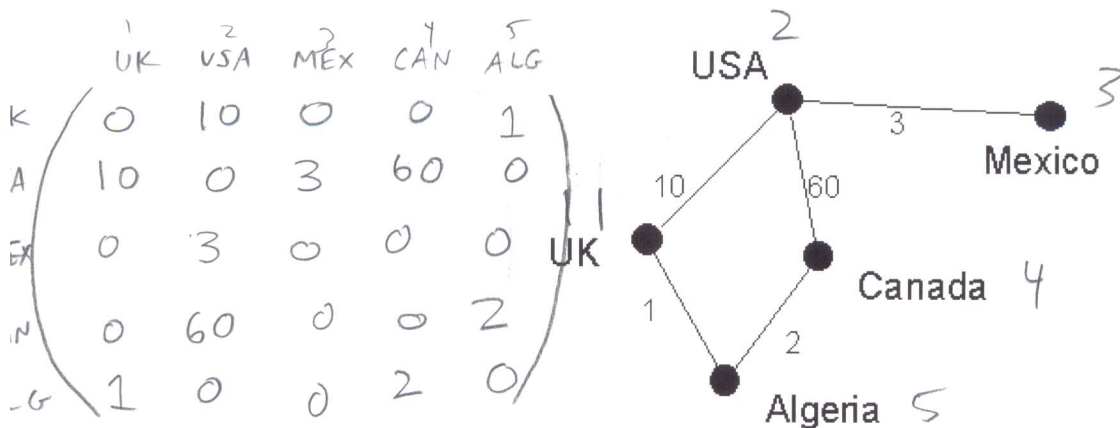
- h. Can the product $(\mathbf{B}_{*3})^T (\mathbf{A}_{3*})^T$ be computed? If so, what is the result?

yes
 $(1 \ 1 \ -1) \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix} = 5$

7. What is the inverse of the matrix $D = \sigma I_3$?

$$D^{-1} = \frac{1}{\sigma} I_3 = \begin{pmatrix} \frac{1}{\sigma} & 0 & 0 \\ 0 & \frac{1}{\sigma} & 0 \\ 0 & 0 & \frac{1}{\sigma} \end{pmatrix}$$

8. For the following graph, number the nodes and write the corresponding adjacency matrix:



ANSWER
DEPENDS ON
ORDER OF
NODES

9. Compute the outer product \mathbf{xy}^T where

$$\mathbf{x} = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} \quad \mathbf{y} = \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\mathbf{xy}^T = \begin{pmatrix} 3 & 3 & -3 & 3 \\ 4 & 4 & -4 & 4 \\ 5 & 5 & -5 & 5 \end{pmatrix}$$

10. Can you say anything about the rank of an outer product in general? Explain your answer.

It will always equal 1 b/c the rows will be multiples of each other \Rightarrow one linearly ind. row.

11. Briefly explain what it means for a matrix to be full rank.

Either the rows are linearly independent or the columns are linearly independent

$$A_{m \times n} \text{ then } \text{rank}(A) = \min(m, n)$$

12. For the following augmented matrices, circle the pivot elements and give the rank of the coefficient matrix along with the number of free variables.

a. $\left(\begin{array}{cccc|c} \textcircled{3} & 2 & 1 & 1 & 2 \\ 0 & \textcircled{2} & 0 & 0 & 1 \\ 0 & 0 & \textcircled{1} & 0 & 5 \end{array} \right)$ rank = 3 # free var = 1

b. $\begin{pmatrix} 1 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$ rank = 2 # free var = 1

c. $\begin{pmatrix} 1 & 2 & 0 & 1 & 0 & | & 2 \\ 0 & 1 & 1 & 1 & 0 & | & 1 \\ 0 & 0 & 0 & 1 & 1 & | & 2 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$ rank = 3 # free var = 2

13. Write the vector \mathbf{v} as a linear combination of each given \mathbf{x} and \mathbf{y} , if possible.

$$\mathbf{v} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

a. $\mathbf{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $\mathbf{y} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $\mathbf{v} = 2\mathbf{x} + 3\mathbf{y}$

b. $\mathbf{x} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$ $\mathbf{y} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$ $\mathbf{v} = -2\mathbf{x} - 3\mathbf{y}$

c. $\mathbf{x} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $\mathbf{y} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$ not possible
 $\mathbf{v} = a\mathbf{x} + b\mathbf{y} \Leftrightarrow \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ system is inconsistent

14. Suppose we measure the heights of 10 people, $\text{person}_1, \text{person}_2, \dots, \text{person}_{10}$.

a. If we create a matrix \mathbf{S} where

$$S_{ij} = \text{height}(\text{person}_i) - \text{height}(\text{person}_j)$$

is the matrix \mathbf{S} symmetric? What is the trace(\mathbf{S})?

NO. $S_{ij} = -S_{ji}$ so not symmetric. Trace(\mathbf{S}) = 0
 Since $S_{ii} = 0$ for all i .

b. If instead we create a matrix \mathbf{G} where

$$G_{ij} = [\text{height}(\text{person}_i) - \text{height}(\text{person}_j)]^2$$

is the matrix \mathbf{G} symmetric? What is the trace(\mathbf{G})?

Yes. $G_{ij} = G_{ji} \Rightarrow$ symmetric. Trace(\mathbf{G}) = 0

15. For the matrix $\mathbf{H} = \mathbf{X}(\mathbf{X}^T \mathbf{\Sigma}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{\Sigma}^{-1}$, use the properties of matrix arithmetic to show that

a. $\mathbf{H}^2 = \mathbf{H}$ $\mathbf{H}^2 = \mathbf{H} \mathbf{H} = \mathbf{X}(\mathbf{X}^T \mathbf{\Sigma}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{\Sigma}^{-1} \mathbf{X}(\mathbf{X}^T \mathbf{\Sigma}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{\Sigma}^{-1}$
 $= \mathbf{X}(\mathbf{X}^T \mathbf{\Sigma}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{\Sigma}^{-1} = \mathbf{H} \quad \checkmark$

b. $\mathbf{H}(\mathbf{I} - \mathbf{H}) = \mathbf{0}$

$= \mathbf{H} - \mathbf{H}^2 = \mathbf{0}$
 by part a!

16. Let

$$\mathbf{U} = (\mathbf{U}_1 | \mathbf{U}_2 | \mathbf{U}_3 | \dots | \mathbf{U}_p) \quad \text{and} \quad \mathbf{V}^T = \begin{pmatrix} \mathbf{V}_1^T \\ \mathbf{V}_2^T \\ \mathbf{V}_3^T \\ \vdots \\ \mathbf{V}_p^T \end{pmatrix}$$

Write the matrix product \mathbf{UV}^T in terms of the columns of \mathbf{U} and the rows of \mathbf{V}^T .

$$\mathbf{UV}^T = \mathbf{U}_1 \mathbf{V}_1^T + \mathbf{U}_2 \mathbf{V}_2^T + \mathbf{U}_3 \mathbf{V}_3^T + \dots + \mathbf{U}_p \mathbf{V}_p^T$$

17. Suppose that \mathbf{u} is a unit vector. Then, $\|\mathbf{u}\|_2 = ?$

1. That's the def. of a unit vector!

18. Let $\mathbf{x} = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$ and $\mathbf{y} = \begin{pmatrix} 0 \\ -1 \\ -3 \end{pmatrix}$. Compute the following:

a. $\|\mathbf{x}\|_2 = \sqrt{1^2 + (-1)^2 + 2^2} = \sqrt{6}$

b. $\|\mathbf{y}\|_1 = |0| + |-1| + |-3| = 4$

c. $\|\mathbf{y}\|_\infty = \max\{|0|, |-1|, |-3|\} = 3$

d. $\|\mathbf{x} - \mathbf{y}\|_2 = \sqrt{(1-0)^2 + (-1+1)^2 + (2+3)^2} = \sqrt{26}$

e. $\|\mathbf{x} - \mathbf{y}\|_1 = |1-0| + |-1+1| + |2+3| = 6$

19. Suppose we have a dataset containing survey data. Individuals were asked to respond 'yes'=1 or 'no'=0 to twenty potential political referendums. Let \mathbf{a} be the vector containing the numerical responses of Individual A and let \mathbf{b} be the vector containing the numerical responses of Individual B (so $\mathbf{a}, \mathbf{b} \in \mathbb{R}^{20}$). Explain in words the interpretation of the quantity

$$\|\mathbf{a} - \mathbf{b}\|_1.$$

the number of referendums upon which individ. A and indiv. B did not agree.

20. **Statistical Formulas Using Linear Algebra Notation.** Almost every statistical formula can be written in a more compact fashion using linear algebra. Most of the elementary formulas involve vector inner products or the Euclidean norm. To begin, we'll introduce the concept of *centering* the data. **Centering** the data means that the mean of a variable is subtracted from each observation. For example, if we have some variable, \mathbf{x} , and 3 observations on that variable:

$$\mathbf{x} = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix}$$

then obviously, $\bar{x} = 3$. The **centered** version of \mathbf{x} would then be

$$\mathbf{x} - \bar{x}\mathbf{e} = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} - \begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}.$$

We simply subtract the mean from every observation so that the new mean of the variable is 0.

Most multivariate textbooks start by saying “*all variable vectors in this textbook are assumed to be centered to have mean zero unless otherwise specified*”. Looking at the most common statistical formulas helps us see why. Try to re-write the following formulas using linear algebra notation, using the vectors \mathbf{x} and \mathbf{y} to represent centered data:

$$\mathbf{x} = \begin{pmatrix} x_1 - \bar{x} \\ x_2 - \bar{x} \\ x_3 - \bar{x} \\ \vdots \\ x_n - \bar{x} \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_1 - \bar{y} \\ y_2 - \bar{y} \\ y_3 - \bar{y} \\ \vdots \\ y_n - \bar{y} \end{pmatrix}$$

For this exercise, keep in mind the following linear algebra constructs, which you should be very familiar with by now:

$$\|\mathbf{a}\| = \sqrt{a_1^2 + a_2^2 + a_3^2 + \cdots + a_n^2}$$

$$\mathbf{a}^T \mathbf{b} = a_1 b_1 + a_2 b_2 + a_3 b_3 + \cdots + a_n b_n$$

- a. Sample standard deviation:

$$s = \frac{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2}}{\sqrt{n-1}} = \boxed{\frac{\|\mathbf{x}\|}{\sqrt{n-1}}}$$

- b. Sample covariance:

$$\text{covariance}(\mathbf{x}, \mathbf{y}) = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y}) = \boxed{\frac{1}{n-1} \mathbf{x}^T \mathbf{y}}$$

c. Correlation coefficient:

$$r_{xy} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \sum_{i=1}^n (y_i - \bar{y})^2}} = \boxed{\frac{x^T y}{\|x\| \cdot \|y\|}}$$

↑
note: this is just
the inner product of
unit vectors!

$$\left(\frac{x}{\|x\|} \right)^T \left(\frac{y}{\|y\|} \right)$$